

# Hand Exoskeleton device



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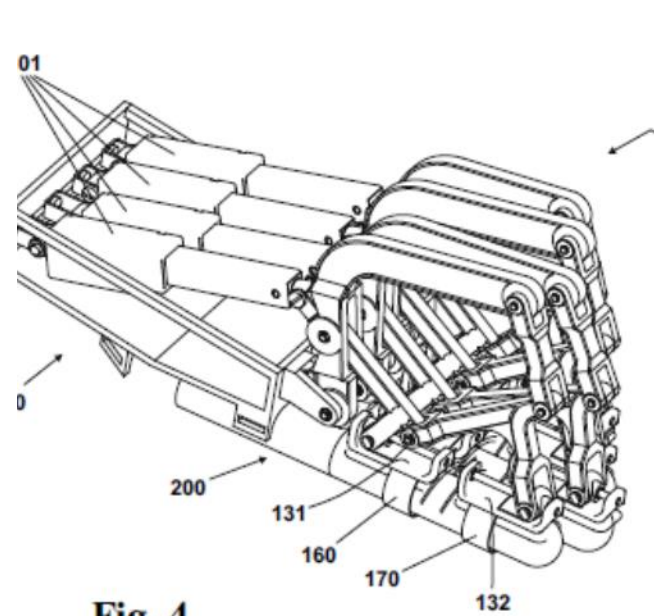
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## Invention

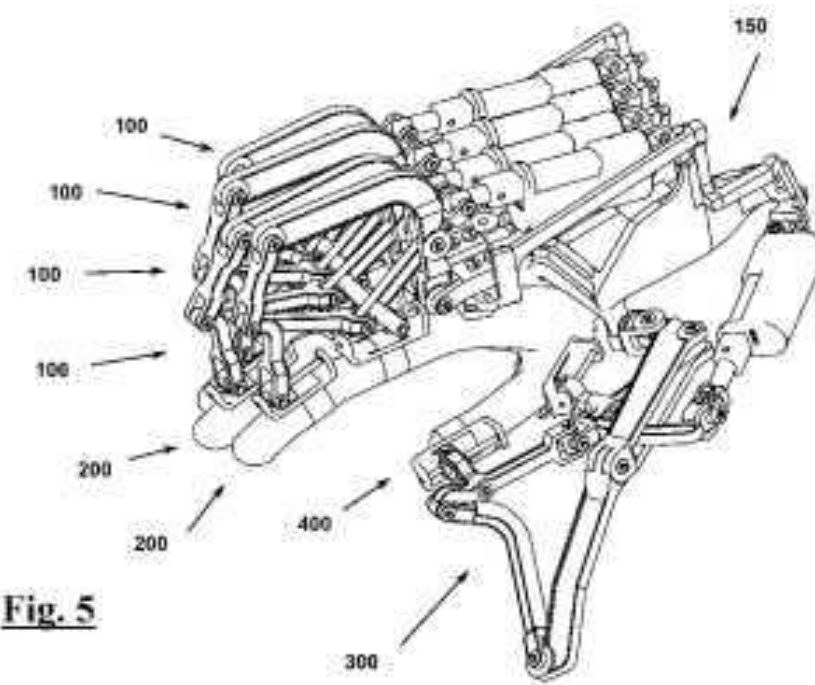


The invention is in the field of wearable exoskeletons for neuromotor and orthopedic robot assisted rehabilitation, for the guidance of the limbs movement during the daily life and is related to an exoskeleton for the guidance and assistance of flex extension movements of fingers and cylindrical objects grasping. An exoskeleton device able to fit different antropometric measurements of the user limbs, capable to reduce the undesirable sollicitations on the anatomic joints, further than a specific and accurate actuation of each finger phalange, so allowing the grasping of objects even if the shape and measurements are unknown before the grasping, in a safe and comfortable easy to wear way, without the need of intial calibration operations.

Drawings  
& pictures



**Fig. 4**



**Fig. 5**



# Industrial applications



- Disabled patient movement assistance during rehabilitation;
- Teleoperation;
- Aptic applications;

Possible  
developments



The research group is interested in industrial partners interested in licensing the technology covered by this patent.

For more information:



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